

On the interaction between (low & high) frequency of (ion-acoustic & Langmuir) waves in plasma via some recent computational schemes

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ABSTRACT

Applying several latest theoretical techniques, the empirical description of the interaction between the high-frequency Langmuir and the low-frequent ion-acoustic waves, derived mathematically by Zakharov's non-dimensional (ZE) equation. These interactions are described in electromagnetic waves, plasma physics, signal processing through optical fibers, coastal engineering, and fluid dynamics. Three modern computing methods are being used to construct several solutions: the extended $\exp(\phi)$ -expansion process, the popular Kudryashov process, and the modified Khather method. Centered on the properties of the Hamilton system, the stability properties of the solutions are investigated. The physical proprieties are illustrated using 3D plots. The originality of the obtained solutions is explored. We demonstrate that we retrieve the old known solutions and we obtain new solutions that have never been found before.

1. Introduction

The dynamics of several natural phenomena at small scales is described by the partial differential equations (PDEs) [1]. For example, the electrical and mechanical proprieties of materials has been explored by solving PDEs [2–4]. PDEs are also governing the dynamics in solid-state physics, [5] plasma physics, [6,7] chemical kinematics, fibers [8, 9], control theory, [10,11], signal processing, electro-circuits [12], biogenetics [13,14], cell recognition [15], cell detection [16], non-linear optics [17,18], Quantum mechanics [19,20] and fluid movement [21, 22]. Due to the increasing need for closed-form solutions that allow

the investigation of many phenomena in the above-mentioned areas, the PDE research field is becoming very active [23–26].

Furthermore not only analytical but also numerical solutions of PDEs become now essential tools for analyzing and simulating complex structures and phenomena in physics [27–34]. Consequently, various systematic techniques have been suggested as useful methods to investigate the closed-form solutions for many physical phenomena, such as the vector iteration method, the Adomian decomposition technique, the homotopic disruption method, the finite element protocol, the ex-function method, the Riccati expansion mechanism, the sech-tanh Method, and so on [35–41].

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Here we are using a mathematical model explains the relationship between the Langmuir high frequency and the acoustic waves [42, 43] of low frequency. This mechanism is defined mathematically by Zakharov's dimensionless type, derived from Zakharov [44,45]. This equation is given by [46]

$$\begin{cases} i\mathfrak{P}_t + \mathfrak{P}_{xx} + w_1 \Psi (|\mathfrak{P}|^2) \mathfrak{P} = \mathfrak{P} \varphi, \\ \varphi_{tt} - \varphi_{xx} = (|\mathfrak{P}|^{2\gamma})_{xx}, \end{cases} \quad (1)$$

where $\mathfrak{P} = \mathfrak{P}(x, t)$, $\varphi = \varphi(x, t)$ respectively, represent the envelope of the high-frequency electric field and the plasma density. While w_1 is arbitrary constant.

For $\Psi (|\mathfrak{P}|^2) = |\mathfrak{P}|^2$, $\gamma = 1$, Eq. (1) becomes

$$\begin{cases} i\mathfrak{P}_t + \mathfrak{P}_{xx} + w_1 |\mathfrak{P}|^2 \mathfrak{P} = \mathfrak{P} \varphi, \\ \varphi_{tt} - \varphi_{xx} = (|\mathfrak{P}|^2)_{xx}, \end{cases} \quad (2)$$

Using the following transformation $\mathfrak{P} = Y e^{i\theta}$, $Y = Y(\mathfrak{F})$, $\mathfrak{F} = x - r_1 t$, $\theta = -r_2 x + r_3 t + r_4$ where r_i , ($i = 1, 2, 3, 4$) are arbitrary constants. on Eq. (2), leads to

$$\begin{cases} (i r_1 Y' - r_3 Y + Y'' - 2 i r_2 Y' - r_2^2 Y + w_1 Y^3 - Y \varphi) e^{i\theta} = 0, \\ (r_1^2 - 1) \varphi'' - (Y^2)'' = 0. \end{cases} \quad (3)$$

For $(r_1 + 2r_2 = 0)$ and twice integration of the second equation in Eq. (3) with zero constant of integration then substituting the result into first equation of the same system, yields

$$Y'' - q_1 Y + q_2 Y^3 = 0, \quad (4)$$

where $\left[q_1 = r_3 + r_2^2, q_2 = \left(w_1 - \frac{1}{r_1^2 - 1} \right) \right]$. Using the homogeneous balance principles on Eq. (4), yields $\left[n + 1 = m \right]$. So that, the explicit solutions of Eq. (4) takes many explicit expressions with respect to the values of n, m . For simplification, we take the following values of them $\left[n = 1 \text{ \& } m = 2 \right]$.

The goal of our research paper is investigating the solitary solutions of the dimensionless form of the Zakharov equation via three recent analytical schemes to explain distinct types of computational solutions. These solutions are deeply helpful to explore more physical and dynamical behavior of the plasma hydrodynamics as well as their further applications in practical life.

The remaining parts of this paper are presented as: Three latest computational schemes are used in Section 2 to determine separate formulations of the dimensionless version of the Zakharov equation and are presented in various forms. In Section 3, we analyze the stability property of the obtained solutions. In Section 4, figures of the obtained solution are illustrated. In Section 5, the novelty of our paper is discussed. We end up by a conclusion in Section 6.

2. Explicit wave solutions of the dimensionless form of the Zakharov equation

In this section, we try to find some distinct stationary wave solutions of Eq. (1) via applying three recent analytical schemes.

2.1. The extended exp(ϕ)-expansion method

By Using the extended exp(ϕ)-expansion method, we obtain the general solutions of Eq. (4) as:

$$Y(\mathfrak{F}) = \frac{\sum_{i=0}^m a_i e^{-i\phi(\mathfrak{F})}}{\sum_{i=0}^n b_i e^{-i\phi(\mathfrak{F})}} = \frac{a_1 e^{-\phi(\mathfrak{F})} + a_2 e^{-2\phi(\mathfrak{F})} + a_0}{b_1 e^{-\phi(\mathfrak{F})} + b_0}, \quad (5)$$

where $[a_0, a_1, a_2, b_0, b_1]$ are arbitrary constants. Also, $\phi(\mathfrak{F})$ is the solution function of the following ordinary differential equation

$$\phi'(\mathfrak{F}) = s_2 e^{\phi(\mathfrak{F})} + \frac{s_3}{e^{\phi(\mathfrak{F})}} + s_1, \quad (6)$$

where $[s_1, s_2, s_3]$ are arbitrary constants to be determined later. Substituting Eq. (5) into Eq. (4) along (6), collecting all terms with the power of $[e^{-i\phi(\mathfrak{F})}, i = 0, 1, 2, \dots]$, and equating them to zero, yield a system of algebraic equations. Solving this system we obtain

Family I

$$\begin{cases} a_1 \rightarrow \frac{a_0 (b_1 s_1 + 2b_0 s_3)}{b_0 s_1}, a_2 \rightarrow \frac{2a_0 b_1 s_3}{b_0 s_1}, \\ q_1 \rightarrow \frac{1}{2} (4s_2 s_3 - s_1^2), q_2 \rightarrow -\frac{b_0^2 s_1^2}{2a_0^2}. \end{cases}$$

Thus, the traveling wave solutions are given in the following formula

When $(s_3 = 1)$

$$\text{For } [s_1^2 - 4s_2 > 0 \text{ \& } s_2 \neq 0]$$

$$\begin{aligned} \mathfrak{P}_1(x, t) &= \frac{a_0 e^{i(r_3 t + r_2(-x) + r_4)} \left(\sqrt{s_1^2 - 4s_2 s_1} \tanh \left(\frac{1}{2} \sqrt{s_1^2 - 4s_2} (\eta - r_1 t + x) \right) + s_1^2 - 4s_2 \right)}{b_0 s_1 \left(\sqrt{s_1^2 - 4s_2} \tanh \left(\frac{1}{2} \sqrt{s_1^2 - 4s_2} (\eta - r_1 t + x) \right) + s_1 \right)}, \end{aligned} \quad (7)$$

$$\begin{aligned} \mathfrak{P}_2(x, t) &= \frac{a_0 e^{i(r_3 t + r_2(-x) + r_4)} \left(\sqrt{s_1^2 - 4s_2 s_1} \coth \left(\frac{1}{2} \sqrt{s_1^2 - 4s_2} (\eta - r_1 t + x) \right) + s_1^2 - 4s_2 \right)}{b_0 s_1 \left(\sqrt{s_1^2 - 4s_2} \coth \left(\frac{1}{2} \sqrt{s_1^2 - 4s_2} (\eta - r_1 t + x) \right) + s_1 \right)}. \end{aligned} \quad (8)$$

$$\text{For } [s_1^2 - 4s_2 > 0 \text{ \& } s_2 = 0 \text{ \& } s_1 \neq 0]$$

$$\mathfrak{P}_3(x, t) = \frac{a_0 e^{i(r_3 t + r_2(-x) + r_4)} \left(e^{s_1(\eta - r_1 t + x)} + 1 \right)}{b_0 \left(e^{s_1(\eta - r_1 t + x)} - 1 \right)}. \quad (9)$$

$$\text{For } [s_1^2 - 4s_2 = 0 \text{ \& } s_2 \neq 0 \text{ \& } s_1 \neq 0]$$

$$\mathfrak{P}_4(x, t) = \frac{2a_0 e^{i(r_3 t + r_2(-x) + r_4)}}{b_0 (s_1 (\eta - r_1 t + x) + 2)}. \quad (10)$$

$$\text{For } [s_1^2 - 4s_2 < 0 \text{ \& } s_2 \neq 0 \text{ \& } s_1 \neq 0]$$

$$\begin{aligned} \mathfrak{P}_5(x, t) &= \frac{a_0 e^{i(r_3 t + r_2(-x) + r_4)} \left(-\sqrt{4s_2 - s_1^2} \tan \left(\frac{1}{2} \sqrt{4s_2 - s_1^2} (\eta - r_1 t + x) \right) + s_1^2 - 4s_2 \right)}{b_0 s_1 \left(s_1 - \sqrt{4s_2 - s_1^2} \tan \left(\frac{1}{2} \sqrt{4s_2 - s_1^2} (\eta - r_1 t + x) \right) \right)}, \end{aligned} \quad (11)$$

$$\mathfrak{P}_6(x, t)$$

$$\begin{aligned} &= \frac{a_0 e^{i(r_3 t + r_2(-x) + r_4)} \left(-\sqrt{4s_2 - s_1^2} \cot \left(\frac{1}{2} \sqrt{4s_2 - s_1^2} (\eta - r_1 t + x) \right) + s_1^2 - 4s_2 \right)}{b_0 s_1 \left(s_1 - \sqrt{4s_2 - s_1^2} \cot \left(\frac{1}{2} \sqrt{4s_2 - s_1^2} (\eta - r_1 t + x) \right) \right)}. \end{aligned} \quad (12)$$

Family II

$$\left[a_0 \rightarrow 0, a_2 \rightarrow \frac{2a_1 s_3}{s_1}, b_0 \rightarrow 0, q_1 \rightarrow \frac{1}{2} (4s_2 s_3 - s_1^2), q_2 \rightarrow -\frac{b_1^2 s_1^2}{2a_1^2} \right]$$

The traveling wave solutions in this case given as

When ($s_3 = 1$)

$$\text{For } \left[s_1^2 - 4s_2 > 0 \text{ \& } s_2 \neq 0 \right]$$

$$\begin{aligned} \mathfrak{P}_7(x, t) &= \frac{a_1 e^{t(r_3 t + r_2(-x) + r_4)} \left(\sqrt{s_1^2 - 4s_2} \tanh \left(\frac{1}{2} \sqrt{s_1^2 - 4s_2} (\eta - r_1 t + x) \right) + s_1^2 - 4s_2 \right)}{b_1 s_1 \left(\sqrt{s_1^2 - 4s_2} \tanh \left(\frac{1}{2} \sqrt{s_1^2 - 4s_2} (\eta - r_1 t + x) \right) + s_1 \right)}, \end{aligned} \quad (13)$$

$$\begin{aligned} \mathfrak{P}_8(x, t) &= \frac{a_1 e^{t(r_3 t + r_2(-x) + r_4)} \left(\sqrt{s_1^2 - 4s_2} \coth \left(\frac{1}{2} \sqrt{s_1^2 - 4s_2} (\eta - r_1 t + x) \right) + s_1^2 - 4s_2 \right)}{b_1 s_1 \left(\sqrt{s_1^2 - 4s_2} \coth \left(\frac{1}{2} \sqrt{s_1^2 - 4s_2} (\eta - r_1 t + x) \right) + s_1 \right)}. \end{aligned} \quad (14)$$

$$\begin{aligned} \text{For } \left[s_1^2 - 4s_2 > 0 \text{ \& } s_2 = 0 \text{ \& } s_1 \neq 0 \right] \\ \mathfrak{P}_9(x, t) &= \frac{a_1 e^{t(r_3 t + r_2(-x) + r_4)} \left(e^{s_1(\eta - r_1 t + x)} + 1 \right)}{b_1 \left(e^{s_1(\eta - r_1 t + x)} - 1 \right)}. \end{aligned} \quad (15)$$

$$\begin{aligned} \text{For } \left[s_1^2 - 4s_2 = 0 \text{ \& } s_2 \neq 0 \text{ \& } s_1 \neq 0 \right] \\ \mathfrak{P}_{10}(x, t) &= \frac{2a_1 e^{t(r_3 t + r_2(-x) + r_4)}}{b_1 (s_1 (\eta - r_1 t + x) + 2)}. \end{aligned} \quad (16)$$

$$\begin{aligned} \text{For } \left[s_1^2 - 4s_2 < 0 \text{ \& } s_2 \neq 0 \text{ \& } s_1 \neq 0 \right] \\ \mathfrak{P}_{11}(x, t) &= \frac{a_1 e^{t(r_3 t + r_2(-x) + r_4)} \left(-\sqrt{4s_2 - s_1^2} \tan \left(\frac{1}{2} \sqrt{4s_2 - s_1^2} (\eta - r_1 t + x) \right) + s_1^2 - 4s_2 \right)}{b_1 s_1 \left(s_1 - \sqrt{4s_2 - s_1^2} \tan \left(\frac{1}{2} \sqrt{4s_2 - s_1^2} (\eta - r_1 t + x) \right) \right)}, \end{aligned} \quad (17)$$

$$\begin{aligned} \mathfrak{P}_{12}(x, t) &= \frac{a_1 e^{t(r_3 t + r_2(-x) + r_4)} \left(-\sqrt{4s_2 - s_1^2} \cot \left(\frac{1}{2} \sqrt{4s_2 - s_1^2} (\eta - r_1 t + x) \right) + s_1^2 - 4s_2 \right)}{b_1 s_1 \left(s_1 - \sqrt{4s_2 - s_1^2} \cot \left(\frac{1}{2} \sqrt{4s_2 - s_1^2} (\eta - r_1 t + x) \right) \right)}. \end{aligned} \quad (18)$$

Family III

$$\left[a_1 \rightarrow 0, a_2 \rightarrow -\frac{4a_0 s_3^2}{s_1^2}, b_1 \rightarrow -\frac{2b_0 s_3}{s_1}, q_1 \rightarrow \frac{1}{2} (4s_2 s_3 - s_1^2), q_2 \rightarrow -\frac{b_0^2 s_1^2}{2a_0^2} \right]$$

then, the traveling wave solutions are given in the following formula

Case one ($s_3 = 1$)

$$\text{For } \left[s_1^2 - 4s_2 > 0 \text{ \& } s_2 \neq 0 \right]$$

$$\begin{aligned} \mathfrak{P}_{13}(x, t) &= (-16a_0 s_2^2 e^{t(r_3 t + r_2(-x) + r_4)}) / \left[b_0 s_1 \left(\sqrt{s_1^2 - 4s_2} \right. \right. \\ &\quad \times \tanh \left(\frac{1}{2} \sqrt{s_1^2 - 4s_2} (\eta - r_1 t + x) \right) + s_1 \Big) \\ &\quad \times \left(\sqrt{s_1^2 - 4s_2} s_1 \tanh \left(\frac{1}{2} \sqrt{s_1^2 - 4s_2} (\eta - r_1 t + x) \right) + s_1^2 + 4s_2 \right) \Big], \end{aligned} \quad (19)$$

$$\begin{aligned} \mathfrak{P}_{14}(x, t) &= (-16a_0 s_2^2 e^{t(r_3 t + r_2(-x) + r_4)}) / \left[b_0 s_1 \left(\sqrt{s_1^2 - 4s_2} \right. \right. \\ &\quad \times \coth \left(\frac{1}{2} \sqrt{s_1^2 - 4s_2} (\eta - r_1 t + x) \right) + s_1 \Big) \\ &\quad \times \left(\sqrt{s_1^2 - 4s_2} s_1 \coth \left(\frac{1}{2} \sqrt{s_1^2 - 4s_2} (\eta - r_1 t + x) \right) + s_1^2 + 4s_2 \right) \Big]. \end{aligned} \quad (20)$$

$$\begin{aligned} \text{For } \left[s_1^2 - 4s_2 > 0 \text{ \& } s_2 = 0 \text{ \& } s_1 \neq 0 \right] \\ \mathfrak{P}_{15}(x, t) &= -\frac{4a_0 e^{t(r_3 t + r_2(-x) + r_4)}}{b_0 \left(e^{s_1(\eta - r_1 t + x)} - 3 \right) \left(e^{s_1(\eta - r_1 t + x)} - 1 \right)}. \end{aligned} \quad (21)$$

$$\begin{aligned} \text{For } \left[s_1^2 - 4s_2 = 0 \text{ \& } s_2 \neq 0 \text{ \& } s_1 \neq 0 \right] \\ \mathfrak{P}_{16}(x, t) &= -\frac{a_0 s_1^2 e^{t(r_3 t + r_2(-x) + r_4)} (\eta - r_1 t + x)^2}{b_0 (s_1 (\eta - r_1 t + x) + 2) (2s_1 (\eta - r_1 t + x) + 2)}. \end{aligned} \quad (22)$$

$$\begin{aligned} \text{For } \left[s_1^2 - 4s_2 < 0 \text{ \& } s_2 \neq 0 \text{ \& } s_1 \neq 0 \right] \\ \mathfrak{P}_{17}(x, t) &= (-16a_0 s_2^2 e^{t(r_3 t + r_2(-x) + r_4)}) / \left[b_0 s_1 \left(s_1 - \sqrt{4s_2 - s_1^2} \right. \right. \\ &\quad \times \tan \left(\frac{1}{2} \sqrt{4s_2 - s_1^2} (\eta - r_1 t + x) \right) \Big) \\ &\quad \times \left(-\sqrt{4s_2 - s_1^2} s_1 \tan \left(\frac{1}{2} \sqrt{4s_2 - s_1^2} (\eta - r_1 t + x) \right) + s_1^2 + 4s_2 \right) \Big], \end{aligned} \quad (23)$$

$$\begin{aligned} \mathfrak{P}_{18}(x, t) &= (-16a_0 s_2^2 e^{t(r_3 t + r_2(-x) + r_4)}) / \left[b_0 s_1 \left(s_1 - \sqrt{4s_2 - s_1^2} \right. \right. \\ &\quad \times \cot \left(\frac{1}{2} \sqrt{4s_2 - s_1^2} (\eta - r_1 t + x) \right) \Big) \\ &\quad \times \left(-\sqrt{4s_2 - s_1^2} s_1 \cot \left(\frac{1}{2} \sqrt{4s_2 - s_1^2} (\eta - r_1 t + x) \right) + s_1^2 + 4s_2 \right) \Big]. \end{aligned} \quad (24)$$

Family IV

$$\left[a_1 \rightarrow \frac{a_0 s_1}{s_2}, a_2 \rightarrow \frac{a_0 s_3}{s_2}, b_1 \rightarrow \frac{2b_0 s_3}{s_1}, q_1 \rightarrow s_1^2 - 4s_2 s_3, q_2 \rightarrow -\frac{8b_0^2 s_2^2 s_3^2}{a_0^2 s_1^2} \right]$$

The traveling wave solutions are then

When ($s_3 = 1$)

$$\text{For } \left[s_1^2 - 4s_2 > 0 \text{ \& } s_2 \neq 0 \right]$$

$$\begin{aligned} \mathfrak{P}_{19}(x, t) &= (4a_0 s_1 s_2 e^{t(r_3 t + r_2(-x) + r_4)}) / \left[b_0 \left(\sqrt{s_1^2 - 4s_2} \right. \right. \\ &\quad \times \tanh \left(\frac{1}{2} \sqrt{s_1^2 - 4s_2} (\eta - r_1 t + x) \right) + s_1 \Big) \\ &\quad \times \left(\sqrt{s_1^2 - 4s_2} s_1 \tanh \left(\frac{1}{2} \sqrt{s_1^2 - 4s_2} (\eta - r_1 t + x) \right) + s_1^2 - 4s_2 \right) \Big], \end{aligned} \quad (25)$$

$$\begin{aligned} \mathfrak{P}_{20}(x, t) &= (4a_0 s_1 s_2 e^{t(r_3 t + r_2(-x) + r_4)}) / \left[b_0 \left(\sqrt{s_1^2 - 4s_2} \right. \right. \\ &\quad \times \coth \left(\frac{1}{2} \sqrt{s_1^2 - 4s_2} (\eta - r_1 t + x) \right) + s_1 \Big) \\ &\quad \times \left(\sqrt{s_1^2 - 4s_2} s_1 \coth \left(\frac{1}{2} \sqrt{s_1^2 - 4s_2} (\eta - r_1 t + x) \right) + s_1^2 - 4s_2 \right) \Big]. \end{aligned} \quad (26)$$

$$\text{For } \left[s_1^2 - 4s_2 = 0 \& s_2 \neq 0 \& s_1 \neq 0 \right]$$

$$\mathfrak{P}_{21}(x, t) = \frac{a_0 s_1^4 e^{t(r_3 t + r_2(-x) + r_4)} (\eta - r_1 t + x)^2}{8b_0 s_2 (s_1 (\eta - r_1 t + x) + 2)}. \quad (27)$$

$$\text{For } \left[s_1^2 - 4s_2 < 0 \& s_2 \neq 0 \& s_1 \neq 0 \right]$$

$$\mathfrak{P}_{22}(x, t) = (4a_0 s_1 s_2 e^{t(r_3 t + r_2(-x) + r_4)}) \left/ \left[b_0 \left(s_1 - \sqrt{4s_2 - s_1^2} \right) \right. \right.$$

$$\times \tan \left(\frac{1}{2} \sqrt{4s_2 - s_1^2} (\eta - r_1 t + x) \right) \left. \right]$$

$$\times \left(-\sqrt{4s_2 - s_1^2} \tan \left(\frac{1}{2} \sqrt{4s_2 - s_1^2} (\eta - r_1 t + x) \right) + s_1^2 - 4s_2 \right), \quad (28)$$

$$\mathfrak{P}_{23}(x, t) = (4a_0 s_1 s_2 e^{t(r_3 t + r_2(-x) + r_4)}) \left/ \left[b_0 \left(s_1 - \sqrt{4s_2 - s_1^2} \right) \right. \right.$$

$$\times \cot \left(\frac{1}{2} \sqrt{4s_2 - s_1^2} (\eta - r_1 t + x) \right) \left. \right]$$

$$\times \left(-\sqrt{4s_2 - s_1^2} \cot \left(\frac{1}{2} \sqrt{4s_2 - s_1^2} (\eta - r_1 t + x) \right) + s_1^2 - 4s_2 \right). \quad (29)$$

Family V

$$\left[a_1 \rightarrow \frac{4a_0 s_3}{s_1}, a_2 \rightarrow \frac{4a_0 s_3^2}{s_1^2}, b_1 \rightarrow \frac{2b_0 s_3}{s_1}, \right.$$

$$\left. q_1 \rightarrow \frac{1}{2} (4s_2 s_3 - s_1^2), q_2 \rightarrow -\frac{b_0^2 s_1^2}{2a_0^2} \right]$$

The traveling wave solutions are given then

When ($s_3 = 1$)

$$\text{For } \left[s_1^2 - 4s_2 > 0 \& s_2 \neq 0 \right]$$

$$\mathfrak{P}_{24}(x, t) = \left(-8a_0 s_2 e^{t(r_3 t + r_2(-x) + r_4)} \left(\sqrt{s_1^2 - 4s_2} s_1 \right. \right.$$

$$\times \tanh \left(\frac{1}{2} \sqrt{s_1^2 - 4s_2} (\eta - r_1 t + x) \right) + s_1^2 - 2s_2 \left. \right)$$

$$\left/ \left[b_0 s_1 \left(\sqrt{s_1^2 - 4s_2} \tanh \left(\frac{1}{2} \sqrt{s_1^2 - 4s_2} (\eta - r_1 t + x) \right) \right. \right. \right. \quad (30)$$

$$+ s_1) \left(\sqrt{s_1^2 - 4s_2} s_1 \right.$$

$$\times \tanh \left(\frac{1}{2} \sqrt{s_1^2 - 4s_2} (\eta - r_1 t + x) \right) + s_1^2 - 4s_2 \left. \right) \left. \right],$$

$$\mathfrak{P}_{25}(x, t) = \left(-8a_0 s_2 e^{t(r_3 t + r_2(-x) + r_4)} \left(\sqrt{s_1^2 - 4s_2} s_1 \right. \right.$$

$$\times \coth \left(\frac{1}{2} \sqrt{s_1^2 - 4s_2} (\eta - r_1 t + x) \right) + s_1^2 - 2s_2 \left. \right)$$

$$\left/ \left[b_0 s_1 \left(\sqrt{s_1^2 - 4s_2} \coth \left(\frac{1}{2} \sqrt{s_1^2 - 4s_2} (\eta - r_1 t + x) \right) + s_1 \right) \right. \right.$$

$$\times \left(\sqrt{s_1^2 - 4s_2} s_1 \coth \left(\frac{1}{2} \sqrt{s_1^2 - 4s_2} (\eta - r_1 t + x) \right) + s_1^2 - 4s_2 \right) \left. \right]. \quad (31)$$

$$\text{For } \left[s_1^2 - 4s_2 > 0 \& s_2 = 0 \& s_1 \neq 0 \right]$$

$$\mathfrak{P}_{26}(x, t) = \frac{1}{b_0} \left[2a_0 \exp(s_1 (\eta - r_1 t + x) + r_3 t + r_2(-x) + r_4) \right.$$

$$\times (\coth(s_1 (\eta - r_1 t + x)) - 1) \left. \right]. \quad (32)$$

$$\text{For } \left[s_1^2 - 4s_2 = 0 \& s_2 \neq 0 \& s_1 \neq 0 \right]$$

$$\mathfrak{P}_{27}(x, t) = -\frac{a_0 s_1 e^{t(r_3 t + r_2(-x) + r_4)} (\eta - r_1 t + x) (s_1 (\eta - r_1 t + x) + 4)}{2b_0 (s_1 (\eta - r_1 t + x) + 2)}. \quad (33)$$

$$\text{For } \left[s_1^2 - 4s_2 < 0 \& s_2 \neq 0 \& s_1 \neq 0 \right]$$

$$\mathfrak{P}_{28}(x, t) = \left(8a_0 s_2 e^{t(r_3 t + r_2(-x) + r_4)} \left(\sqrt{4s_2 - s_1^2} s_1 \right. \right.$$

$$\tan \left(\frac{1}{2} \sqrt{4s_2 - s_1^2} (\eta - r_1 t + x) \right) - s_1^2 + 2s_2 \left. \right)$$

$$\left/ \left[b_0 s_1 \left(s_1 - \sqrt{4s_2 - s_1^2} \tan \left(\frac{1}{2} \sqrt{4s_2 - s_1^2} (\eta - r_1 t + x) \right) \right) \right. \right.$$

$$\times \left(-\sqrt{4s_2 - s_1^2} \tan \left(\frac{1}{2} \sqrt{4s_2 - s_1^2} (\eta - r_1 t + x) \right) + s_1^2 - 4s_2 \right) \left. \right], \quad (34)$$

$$\mathfrak{P}_{29}(x, t) = \left(8a_0 s_2 e^{t(r_3 t + r_2(-x) + r_4)} \left(\sqrt{4s_2 - s_1^2} s_1 \right. \right.$$

$$\times \cot \left(\frac{1}{2} \sqrt{4s_2 - s_1^2} (\eta - r_1 t + x) \right) - s_1^2 + 2s_2 \left. \right)$$

$$\left/ \left[b_0 s_1 \left(s_1 - \sqrt{4s_2 - s_1^2} \cot \left(\frac{1}{2} \sqrt{4s_2 - s_1^2} (\eta - r_1 t + x) \right) \right) \right. \right.$$

$$\times \left(-\sqrt{4s_2 - s_1^2} \cot \left(\frac{1}{2} \sqrt{4s_2 - s_1^2} (\eta - r_1 t + x) \right) + s_1^2 - 4s_2 \right) \left. \right]. \quad (35)$$

Family VI

$$\left[a_1 \rightarrow \frac{2a_0 s_1 s_3}{s_1^2 - 2s_2 s_3}, a_2 \rightarrow -\frac{2a_0 s_3^2}{2s_2 s_3 - s_1^2}, b_1 \rightarrow \frac{2b_0 s_3}{s_1}, \right.$$

$$\left. q_1 \rightarrow -2(s_1^2 - 4s_2 s_3), q_2 \rightarrow -\frac{2b_0^2 (s_1^2 - 2s_2 s_3)^2}{a_0^2 s_1^2} \right]$$

The traveling wave solutions are then

When ($s_3 = 1$)

$$\text{For } \left[s_1^2 - 4s_2 > 0 \& s_2 \neq 0 \right]$$

$$\mathfrak{P}_{30}(x, t)$$

$$= \frac{a_0 e^{t(r_3 t + r_2(-x) + r_4)} \left(1 - \frac{4s_2 \left(\sqrt{s_1^2 - 4s_2} s_1 \tanh \left(\frac{1}{2} \sqrt{s_1^2 - 4s_2} (\eta - r_1 t + x) \right) + s_1^2 - 2s_2 \right)}{(s_1^2 - 2s_2) \left(\sqrt{s_1^2 - 4s_2} \tanh \left(\frac{1}{2} \sqrt{s_1^2 - 4s_2} (\eta - r_1 t + x) \right) + s_1 \right)^2} \right)}{b_0 \left(1 - \frac{4s_2}{\sqrt{s_1^2 - 4s_2} s_1 \tanh \left(\frac{1}{2} \sqrt{s_1^2 - 4s_2} (\eta - r_1 t + x) \right) + s_1^2} \right)}, \quad (36)$$

$$\mathfrak{P}_{31}(x, t)$$

$$= \frac{a_0 e^{t(r_3 t + r_2(-x) + r_4)} \left(1 - \frac{4s_2 \left(\sqrt{s_1^2 - 4s_2} s_1 \coth \left(\frac{1}{2} \sqrt{s_1^2 - 4s_2} (\eta - r_1 t + x) \right) + s_1^2 - 2s_2 \right)}{(s_1^2 - 2s_2) \left(\sqrt{s_1^2 - 4s_2} \coth \left(\frac{1}{2} \sqrt{s_1^2 - 4s_2} (\eta - r_1 t + x) \right) + s_1 \right)^2} \right)}{b_0 \left(1 - \frac{4s_2}{\sqrt{s_1^2 - 4s_2} s_1 \coth \left(\frac{1}{2} \sqrt{s_1^2 - 4s_2} (\eta - r_1 t + x) \right) + s_1^2} \right)}. \quad (37)$$

$$\text{For } \left[s_1^2 - 4s_2 > 0 \& s_2 = 0 \& s_1 \neq 0 \right]$$

$$\mathfrak{P}_{32}(x, t) = \frac{1}{b_0} (a_0 e^{t(r_3 t + r_2(-x) + r_4)} \coth(s_1 (\eta - r_1 t + x))). \quad (38)$$

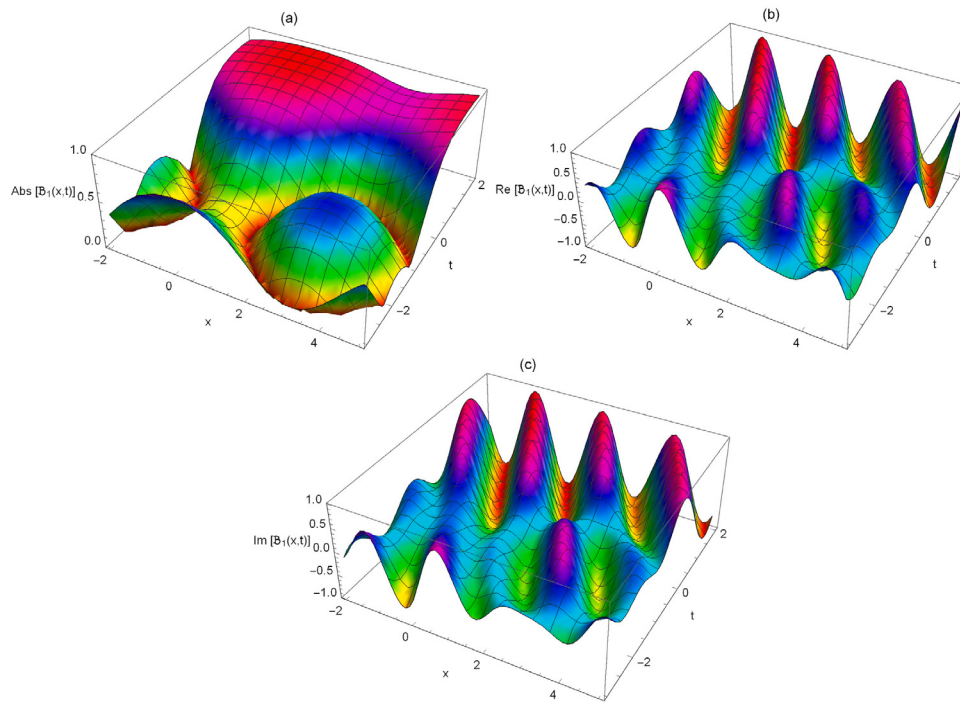


Fig. 1. Numerical simulation of absolute, real, and imaginary Eq. (7) in three-dimensional plots.

$$\text{For } \left[s_1^2 - 4s_2 = 0 \text{ \& } s_2 \neq 0 \text{ \& } s_1 \neq 0 \right]$$

$$\mathfrak{P}_{33}(x, t) = \frac{1}{4b_0} \left[a_0 e^{t(r_3 t + r_2(-x) + r_4)} (s_1(\eta - r_1 t + x) + 2) \right. \\ \left. \times \left(2 - \frac{s_1^3(\eta - r_1 t + x)(s_1(\eta - r_1 t + x) + 4)}{(s_1^2 - 2s_2)(s_1(\eta - r_1 t + x) + 2)^2} \right) \right]. \quad (39)$$

$$\text{For } \left[s_1^2 - 4s_2 < 0 \text{ \& } s_2 \neq 0 \text{ \& } s_1 \neq 0 \right]$$

$$\mathfrak{P}_{34}(x, t) = \frac{a_0 e^{t(r_3 t + r_2(-x) + r_4)} \left(\frac{4s_2(\sqrt{4s_2 - s_1^2} s_1 \tan(\frac{1}{2} \sqrt{4s_2 - s_1^2}(\eta - r_1 t + x)) - s_1^2 + 2s_2)}{(s_1^2 - 2s_2)(s_1 - \sqrt{4s_2 - s_1^2} \tan(\frac{1}{2} \sqrt{4s_2 - s_1^2}(\eta - r_1 t + x)))^2} + 1 \right)}{b_0 \left(1 - \frac{4s_2}{s_1^2 - s_1 \sqrt{4s_2 - s_1^2} \tan(\frac{1}{2} \sqrt{4s_2 - s_1^2}(\eta - r_1 t + x))} \right)}, \quad (40)$$

$$\mathfrak{P}_{35}(x, t) = \frac{a_0 e^{t(r_3 t + r_2(-x) + r_4)} \left(\frac{4s_2(\sqrt{4s_2 - s_1^2} s_1 \cot(\frac{1}{2} \sqrt{4s_2 - s_1^2}(\eta - r_1 t + x)) - s_1^2 + 2s_2)}{(s_1^2 - 2s_2)(s_1 - \sqrt{4s_2 - s_1^2} \cot(\frac{1}{2} \sqrt{4s_2 - s_1^2}(\eta - r_1 t + x)))^2} + 1 \right)}{b_0 \left(1 - \frac{4s_2}{s_1^2 - s_1 \sqrt{4s_2 - s_1^2} \cot(\frac{1}{2} \sqrt{4s_2 - s_1^2}(\eta - r_1 t + x))} \right)}. \quad (41)$$

Note that, when $(s_1 = 1)$ **and** $(s_2 = s_1 = 0)$ **for all above families** [I, II, III, IV, V, VI], **we get a trivial solutions.**

2.2. The generalized Kudryashov method

By applying the generalized Kudryashov method, in Eq. (1) we construct the general solution of Eq. (4) as:

$$Y(\mathfrak{F}) = \frac{\sum_{i=0}^m a_i Q(\mathfrak{F})^i}{\sum_{j=0}^n b_j \Omega(\mathfrak{F})^j} = \frac{a_2 \Omega(\mathfrak{F})^2 + a_1 \Omega(\mathfrak{F}) + a_0}{b_1 \Omega(\mathfrak{F}) + b_0}, \quad (42)$$

where $[a_0, a_1, a_2, b_0, b_1]$ are arbitrary constants. Also, $\Omega(\mathfrak{F})$ is the solution function of the following ordinary differential equation

$$\Omega'(\mathfrak{F}) = \Omega(\mathfrak{F})^2 - \Omega(\mathfrak{F}), \quad (43)$$

Substituting Eq. (42) into Eq. (4) along (43), collecting all terms with the power of $[\Omega(\mathfrak{F})^i, i = 0, 1, 2, \dots]$, and equating them to zero, yield a system of algebraic equations. Their solutions are given as following:

Family I

$$\left[a_0 \rightarrow \frac{a_1 b_0}{b_1 - 2b_0}, a_2 \rightarrow -\frac{2a_1 b_1}{b_1 - 2b_0}, q_1 \rightarrow -\frac{1}{2}, q_2 \rightarrow -\frac{(b_1 - 2b_0)^2}{2a_1^2} \right]$$

Family II

$$\left[a_0 \rightarrow -\frac{a_1}{2}, a_2 \rightarrow -a_1, b_1 \rightarrow -2b_0, q_1 \rightarrow -2, q_2 \rightarrow -\frac{8b_0^2}{a_1^2} \right]$$

Family III

$$\left[a_0 \rightarrow -\frac{a_1}{4}, a_2 \rightarrow -a_1, b_1 \rightarrow -2b_0, q_1 \rightarrow -\frac{1}{2}, q_2 \rightarrow -\frac{8b_0^2}{a_1^2} \right]$$

Family IV

$$\left[a_1 \rightarrow 0, a_2 \rightarrow -4a_0, b_1 \rightarrow 2b_0, q_1 \rightarrow -\frac{1}{2}, q_2 \rightarrow -\frac{b_0^2}{2a_0^2} \right]$$

Family V

$$\left[a_0 \rightarrow \frac{ib_0}{\sqrt{2}\sqrt{q_2}}, a_1 \rightarrow \frac{i(b_1 - 2b_0)}{\sqrt{2}\sqrt{q_2}}, a_2 \rightarrow -\frac{i\sqrt{2}b_1}{\sqrt{q_2}}, q_1 \rightarrow -\frac{1}{2} \right]$$

Family VI

$$\left[a_0 \rightarrow 0, a_1 \rightarrow -\frac{ib_1}{\sqrt{2}\sqrt{q_2}}, a_2 \rightarrow \frac{i\sqrt{2}b_1}{\sqrt{q_2}}, b_0 \rightarrow 0, q_1 \rightarrow -\frac{1}{2} \right]$$

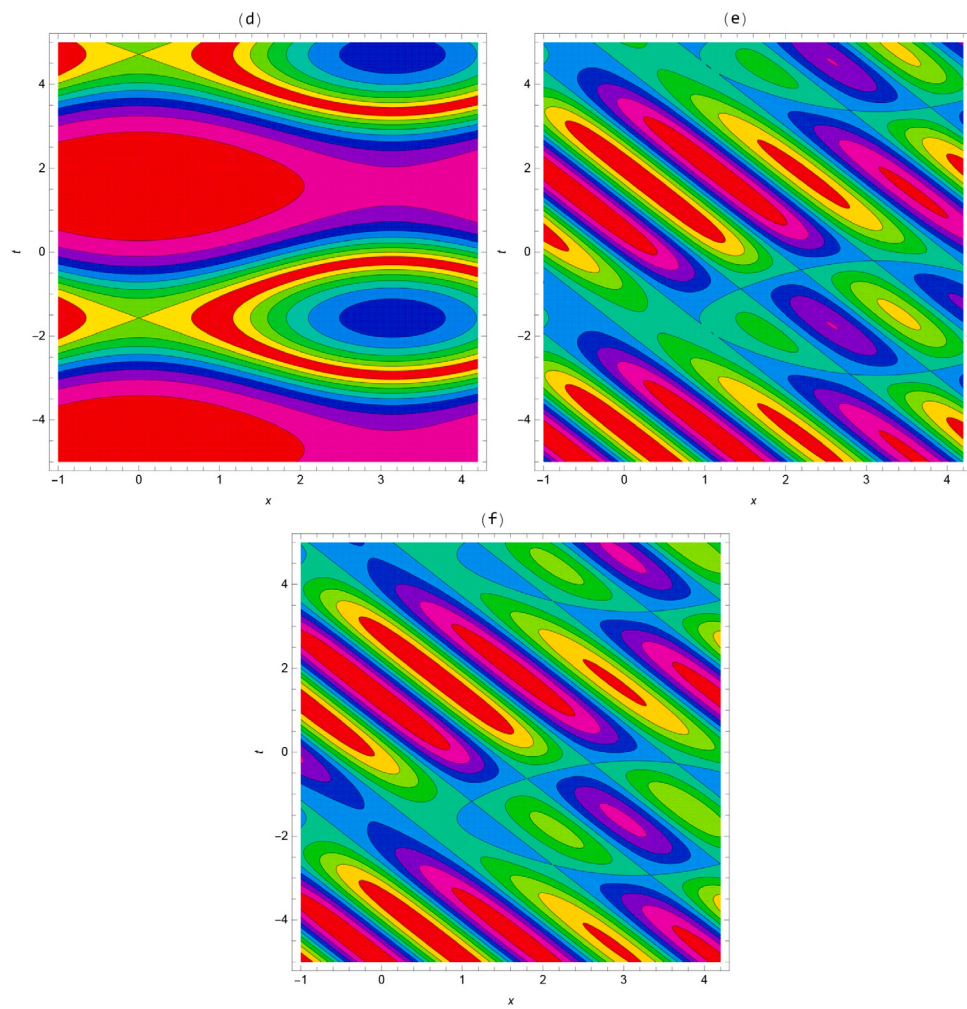


Fig. 2. Numerical simulation of absolute, real, and imaginary Eq. (7) in contour plots.

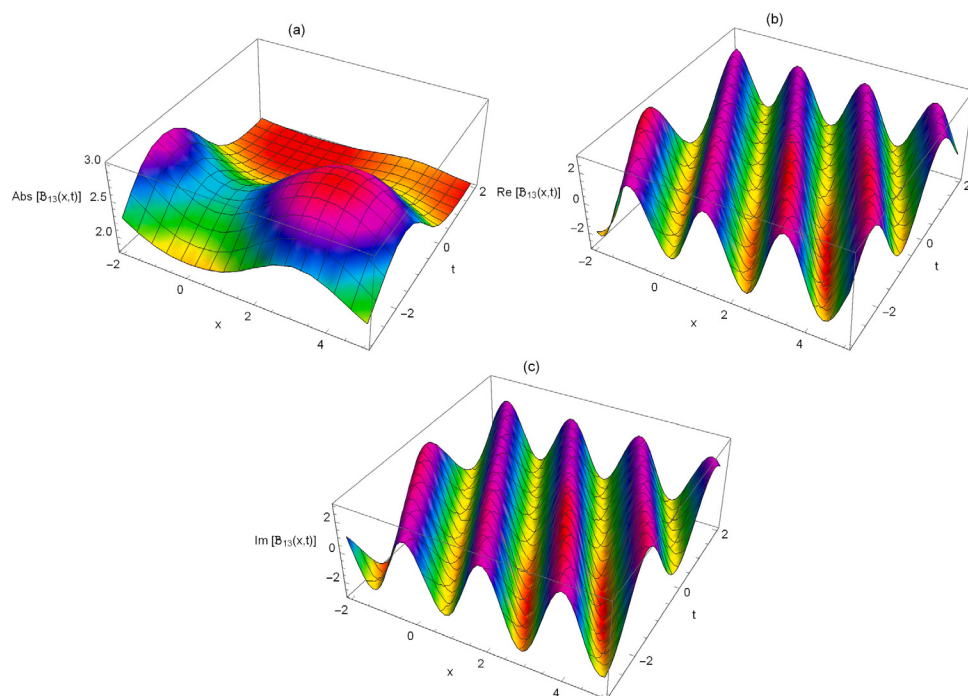


Fig. 3. Numerical simulation of absolute, real, and imaginary Eq. (19) in three-dimensional plots.

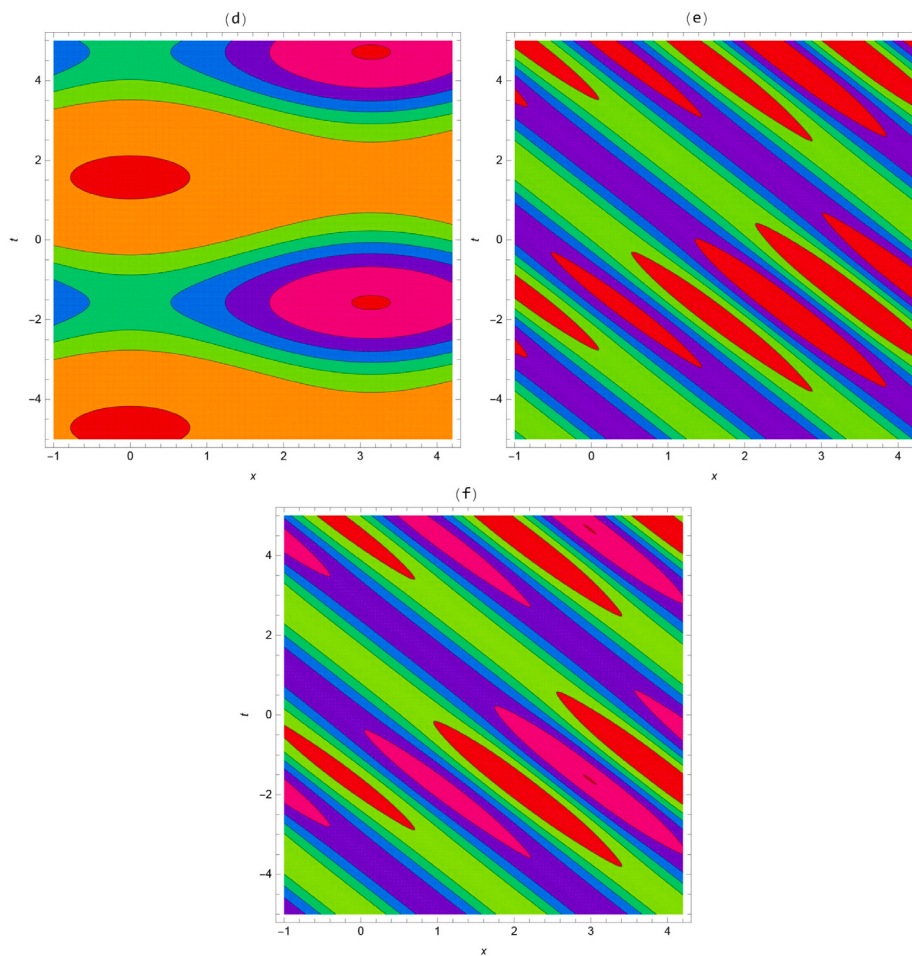


Fig. 4. Numerical simulation of absolute, real, and imaginary Eq. (19) in contour plots.

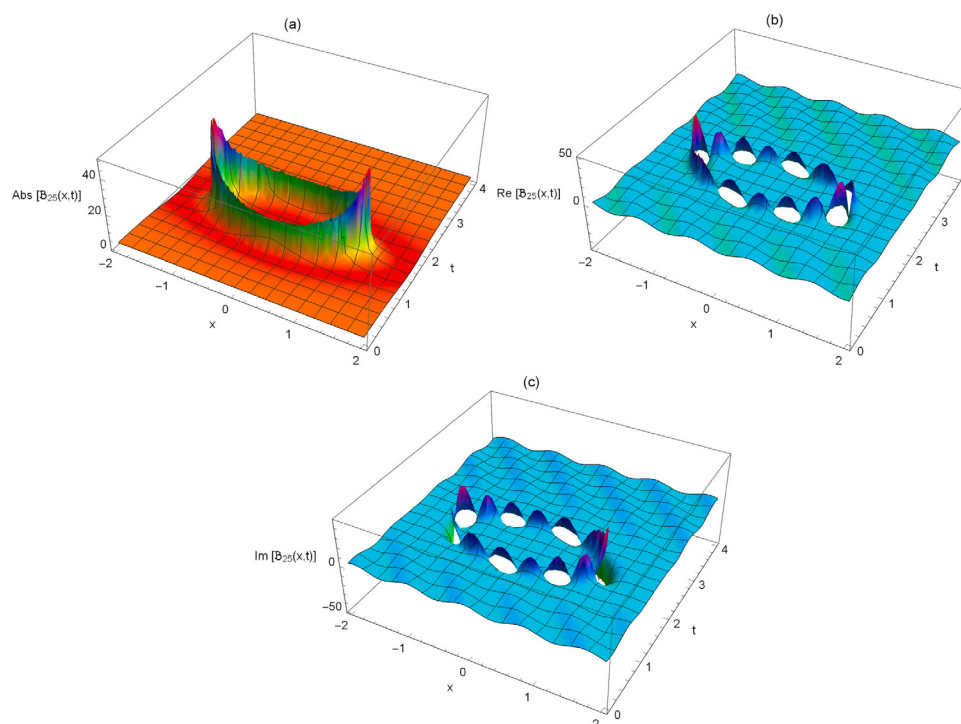


Fig. 5. Numerical simulation of absolute, real, and imaginary Eq. (31) in three-dimensional plots.

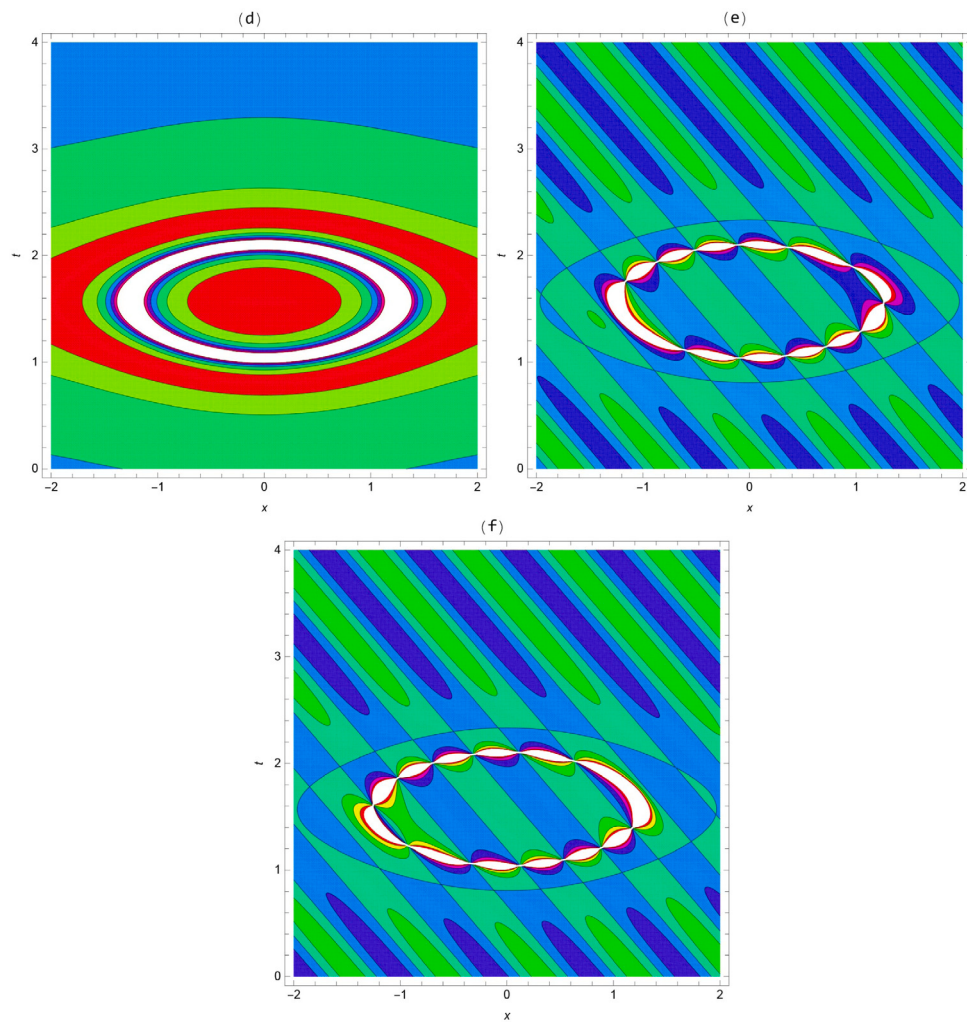


Fig. 6. Numerical simulation of absolute, real, and imaginary Eq. (31) in contour plots.

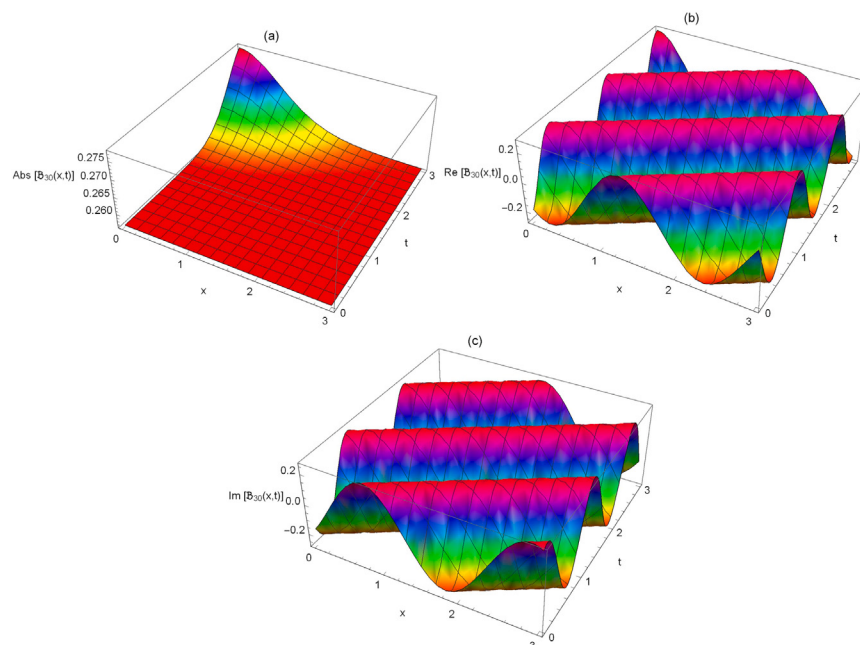


Fig. 7. Numerical simulation of absolute, real, and imaginary Eq. (36) in three-dimensional plots.

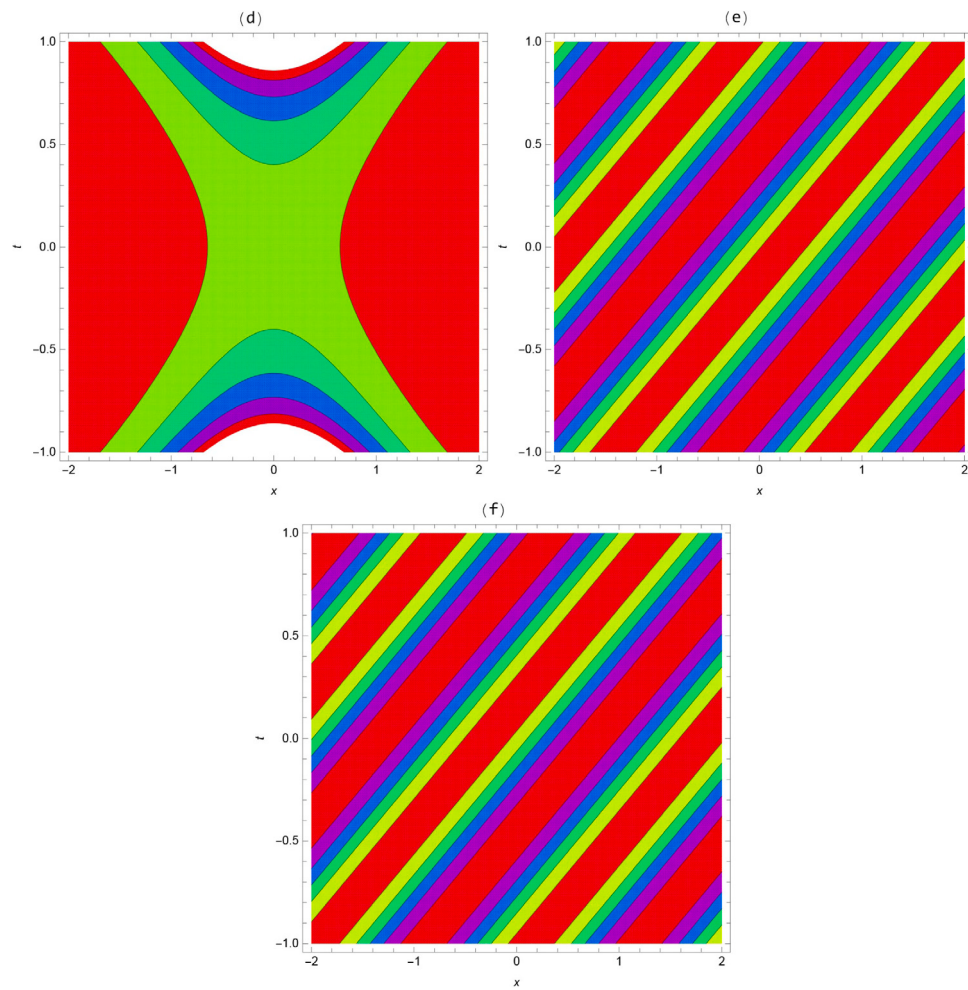


Fig. 8. Numerical simulation of absolute, real, and imaginary Eq. (36) in contour plot plots.

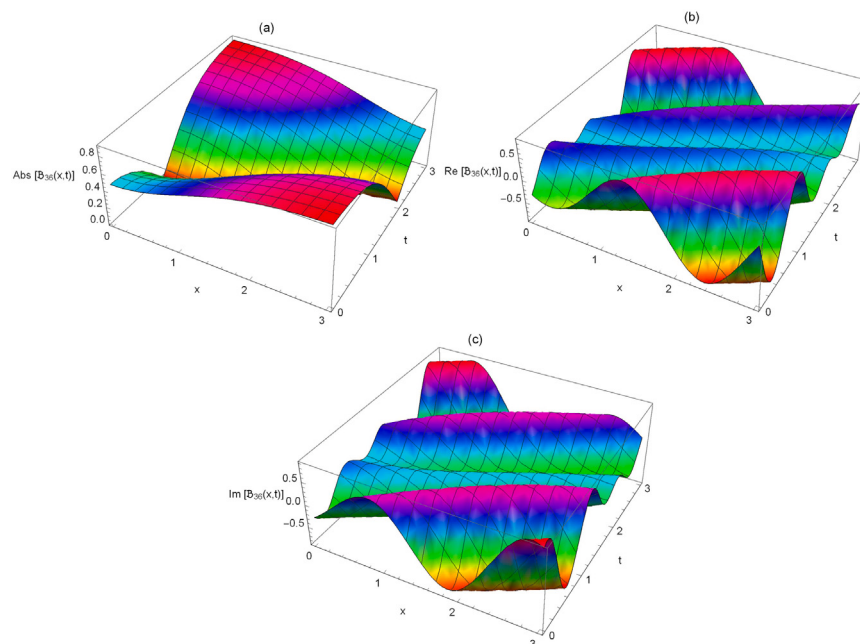


Fig. 9. Numerical simulation of absolute, real, and imaginary Eq. (44) in three-dimensional plots.

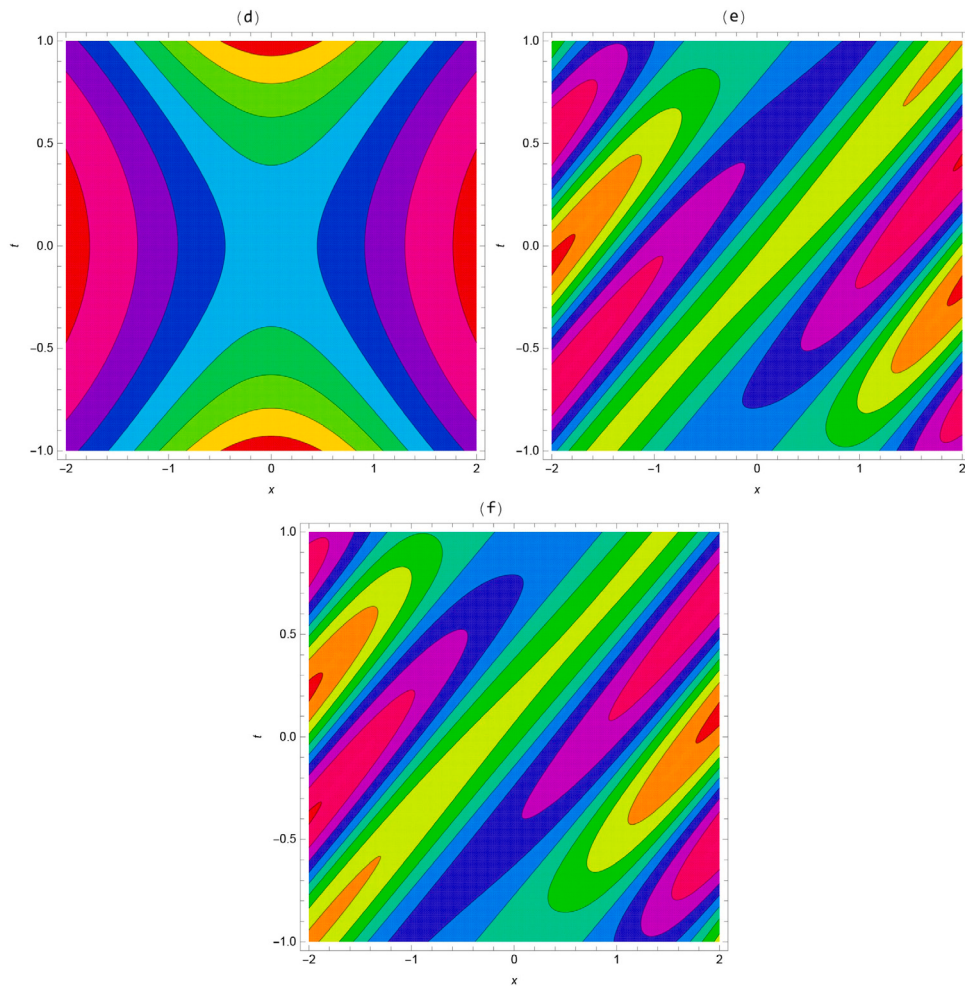


Fig. 10. Numerical simulation of absolute, real, and imaginary Eq. (44) in contour plots.

Family VII

$$\left[a_0 \rightarrow 0, a_1 \rightarrow -\frac{2i\sqrt{2}b_0}{\sqrt{q_2}}, a_2 \rightarrow \frac{2i\sqrt{2}b_0}{\sqrt{q_2}}, b_1 \rightarrow -2b_0, q_1 \rightarrow 1. \right]$$

Family VIII

$$\left[a_0 \rightarrow \frac{i\sqrt{2}b_0}{\sqrt{q_2}}, a_1 \rightarrow -\frac{2i\sqrt{2}b_0}{\sqrt{q_2}}, a_2 \rightarrow \frac{2i\sqrt{2}b_0}{\sqrt{q_2}}, b_1 \rightarrow -2b_0, q_1 \rightarrow -2. \right]$$

Family IX

$$\left[a_0 \rightarrow \frac{ib_0}{\sqrt{2}\sqrt{q_2}}, a_1 \rightarrow 0, a_2 \rightarrow -\frac{2i\sqrt{2}b_0}{\sqrt{q_2}}, b_1 \rightarrow 2b_0, q_1 \rightarrow -\frac{1}{2}. \right]$$

Thus, the traveling wave solutions are respectively given in the following formulas

$$\mathfrak{P}_{36}(x, t) = \frac{a_1 e^{i(r_3 t + r_2(-x) + r_4)} (e^{r_1 t} - A e^x)}{(2b_0 - b_1) (A e^x + e^{r_1 t})}. \quad (44)$$

$$\mathfrak{P}_{37}(x, t) = \frac{a_1 e^{i(r_3 t + r_2(-x) + r_4)} (A^2 e^{2x} + e^{2r_1 t})}{2b_0 (e^{2r_1 t} - A^2 e^{2x})}. \quad (45)$$

$$\mathfrak{P}_{38}(x, t) = \frac{a_1 e^{i(r_3 t + r_2(-x) + r_4)} (e^{r_1 t} - A e^x)}{4b_0 (A e^x + e^{r_1 t})}. \quad (46)$$

$$\mathfrak{P}_{39}(x, t) = -\frac{a_0 e^{i(r_3 t + r_2(-x) + r_4)} (e^{r_1 t} - A e^x)}{b_0 (A e^x + e^{r_1 t})}. \quad (47)$$

$$\mathfrak{P}_{40}(x, t) = -\frac{i e^{i(r_3 t + r_2(-x) + r_4)} (e^{r_1 t} - A e^x)}{\sqrt{2}\sqrt{q_2} (A e^x + e^{r_1 t})}. \quad (48)$$

$$\mathfrak{P}_{41}(x, t) = \frac{i e^{i(r_3 t + r_2(-x) + r_4)} (e^{r_1 t} - A e^x)}{\sqrt{2}\sqrt{q_2} (A e^x + e^{r_1 t})}. \quad (49)$$

$$\mathfrak{P}_{42}(x, t) = \frac{2i\sqrt{2}A e^{r_1 t + i r_3 t - i r_2 x + i r_4 + x}}{\sqrt{q_2} (e^{2r_1 t} - A^2 e^{2x})}. \quad (50)$$

$$\mathfrak{P}_{43}(x, t) = -\frac{i\sqrt{2} e^{i(r_3 t + r_2(-x) + r_4)} (A^2 e^{2x} + e^{2r_1 t})}{\sqrt{q_2} (e^{2r_1 t} - A^2 e^{2x})}. \quad (51)$$

$$\mathfrak{P}_{45}(x, t) = -\frac{i e^{i(r_3 t + r_2(-x) + r_4)} (e^{r_1 t} - A e^x)}{\sqrt{2}\sqrt{q_2} (A e^x + e^{r_1 t})}. \quad (52)$$

2.3. The modified Khater method

Handling Eq. (1) by applying the modified Khater method, we obtain the general solution of Eq. (4) in the following formula

$$Y(\mathfrak{F}) = \sum_{i=1}^n a_i \Gamma^i \mathfrak{F}(\mathfrak{F}) + \sum_{i=1}^n b_i \Gamma^{-i} \mathfrak{F}(\mathfrak{F}) + a_0 = a_1 \Gamma^{\mathfrak{F}(\mathfrak{F})} + a_0 + b_1 \Gamma^{-\mathfrak{F}(\mathfrak{F})}, \quad (53)$$

where $[a_0, a_1, b_1, \Gamma (\Gamma \neq 0, \Gamma \neq 1)]$ are arbitrary constants. Also, $\mathfrak{F}(\mathfrak{F})$ is the solution function of the following ordinary differential equation

$$\mathfrak{F}'(\mathfrak{F}) = \frac{1}{\ln(\Gamma)} \left[v_3 \Gamma^{\mathfrak{F}(\mathfrak{F})} + v_1 \Gamma^{-\mathfrak{F}(\mathfrak{F})} + v_2 \right], \quad (54)$$

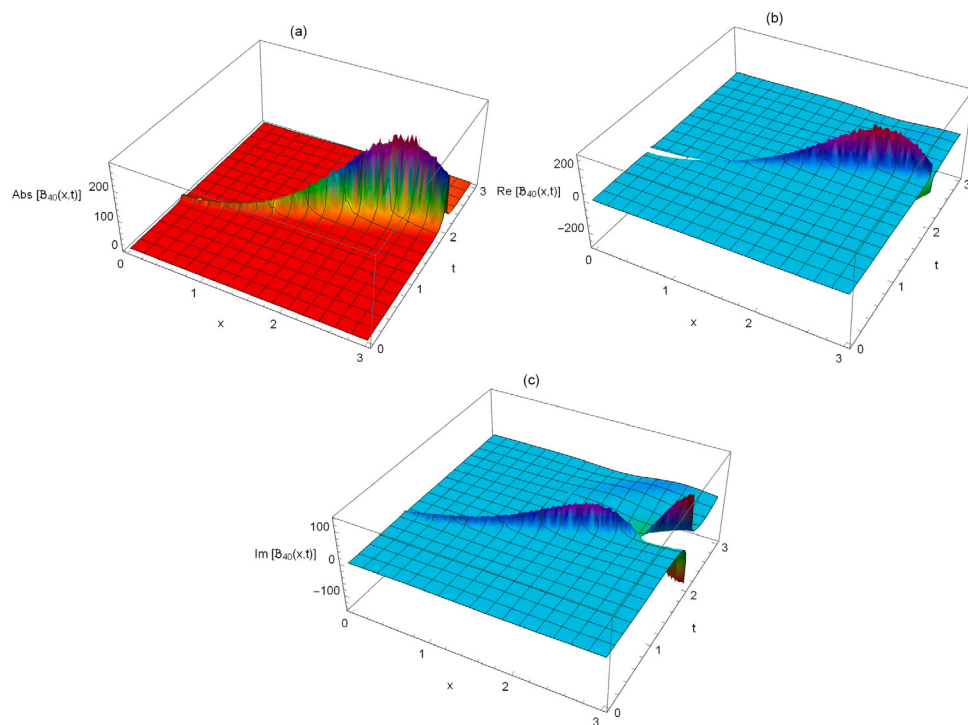


Fig. 11. Numerical simulation of absolute, real, and imaginary Eq. (48) in three-dimensional plots.

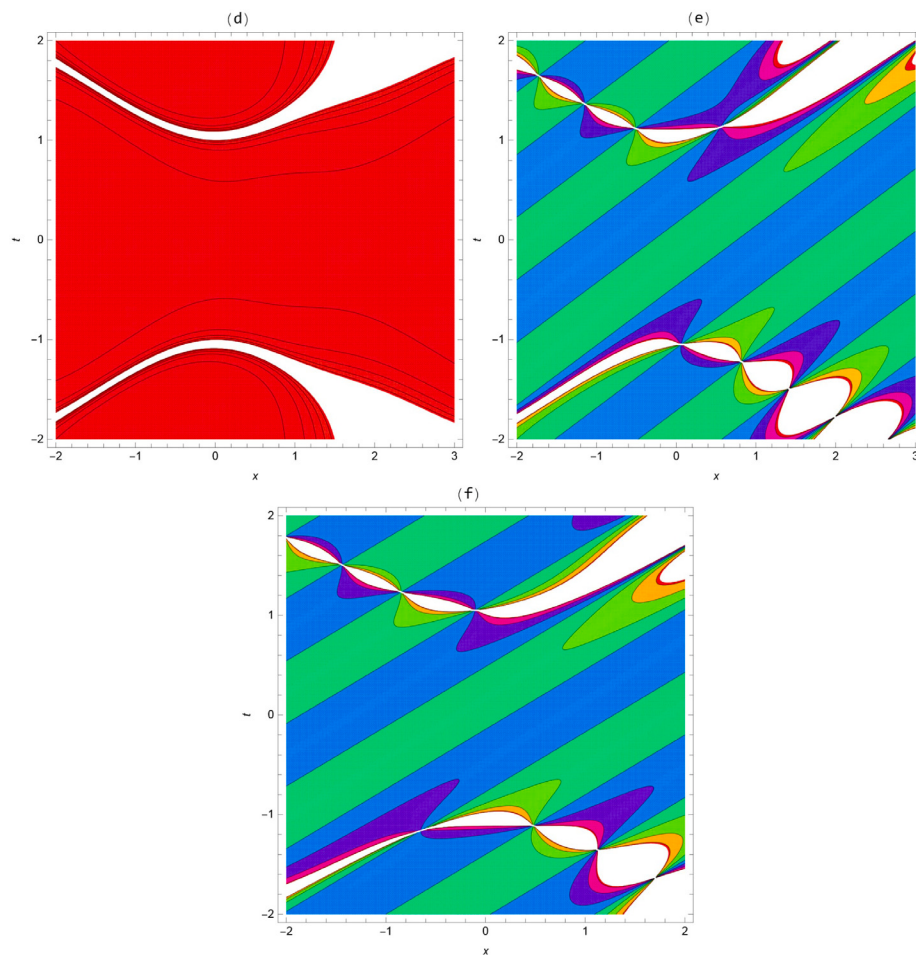


Fig. 12. Numerical simulation of absolute, real, and imaginary Eq. (48) in contour plots.

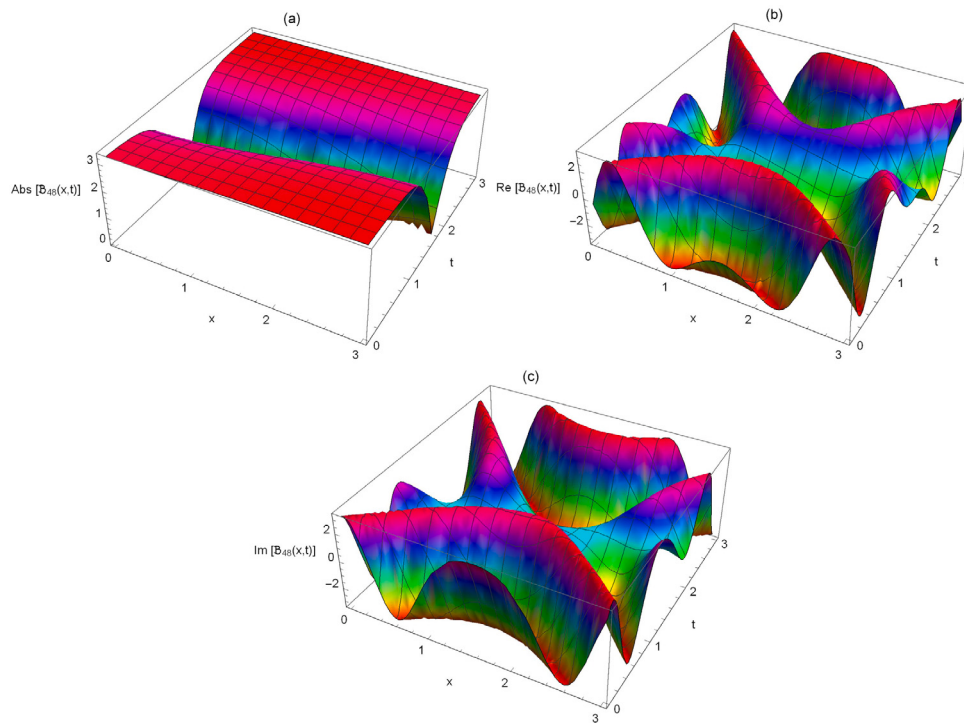


Fig. 13. Numerical simulation of absolute, real, and imaginary Eq. (57) in three-dimensional plots.

where $[v_1, v_2, v_3]$ are arbitrary constants to be determined later. Substituting Eq. (53) into Eq. (4) along (54), collecting all terms with the power of $[r^i \mathfrak{B}^i], i = 0, 1, 2, \dots$, and equating them to zero, yield a system of algebraic equations. Solving this system we get

Family I

$$\left[a_1 \rightarrow \frac{2a_0v_3}{v_2}, b_1 \rightarrow 0, q_1 \rightarrow \frac{1}{2}(4v_3v_1 - v_2^2), q_2 \rightarrow -\frac{v_2^2}{2a_0^2} \right]$$

Thus, the traveling wave solutions are given in the following formulas

$$\text{For } [v_2^2 - 4v_1v_3 < 0 \text{ \& } v_3 \neq 0]$$

$$\mathfrak{P}_{46}(x, t) = \frac{1}{v_2} \left(a_0 \sqrt{4v_1v_3 - v_2^2} e^{i(r_3t + r_2(-x) + r_4)} \tan \left(\frac{1}{2} \sqrt{4v_1v_3 - v_2^2} (x - r_1t) \right) \right), \quad (55)$$

$$\mathfrak{P}_{47}(x, t) = \frac{1}{v_2} \left(a_0 \sqrt{4v_1v_3 - v_2^2} e^{i(r_3t + r_2(-x) + r_4)} \cot \left(\frac{1}{2} \sqrt{4v_1v_3 - v_2^2} (x - r_1t) \right) \right). \quad (56)$$

$$\text{For } [v_2^2 - 4v_1v_3 < 0 \text{ \& } v_3 \neq 0]$$

$$\mathfrak{P}_{48}(x, t) = \frac{-1}{v_2} \left(a_0 \sqrt{v_2^2 - 4v_1v_3} e^{i(r_3t + r_2(-x) + r_4)} \tanh \left(\frac{1}{2} \sqrt{v_2^2 - 4v_1v_3} (x - r_1t) \right) \right), \quad (57)$$

$$\mathfrak{P}_{49}(x, t) = \frac{-1}{v_2} \left(a_0 \sqrt{v_2^2 - 4v_1v_3} e^{i(r_3t + r_2(-x) + r_4)} \coth \left(\frac{1}{2} \sqrt{v_2^2 - 4v_1v_3} (x - r_1t) \right) \right). \quad (58)$$

$$\text{For } [v_2 = v_3 = \kappa \text{ \& } v_1 = 0]$$

$$\mathfrak{P}_{50}(x, t) = a_0 (-e^{i(r_3t + r_2(-x) + r_4)}) \coth \left(\frac{1}{2} \kappa (x - r_1t) \right). \quad (59)$$

$$\text{For } [v_1 = 0 \text{ \& } v_2 \neq 0 \text{ \& } v_3 \neq 0]$$

$$\mathfrak{P}_{51}(x, t) = -\frac{a_0 e^{i(r_3t + r_2(-x) + r_4)} (v_3 e^{v_2(x - r_1t)} + 2)}{v_3 e^{v_2(x - r_1t)} - 2}. \quad (60)$$

Family II

$$\left[a_1 \rightarrow 0, b_1 \rightarrow \frac{2a_0v_1}{v_2}, q_1 \rightarrow \frac{1}{2}(4v_3v_1 - v_2^2), q_2 \rightarrow -\frac{v_2^2}{2a_0^2} \right]$$

Thus, the traveling wave solutions are given in the following formulas

$$\text{For } [v_2^2 - 4v_1v_3 < 0 \text{ \& } v_3 \neq 0]$$

$$\mathfrak{P}_{52}(x, t) = a_0 e^{i(r_3t + r_2(-x) + r_4)} \times \left[1 - \frac{4v_1v_3}{v_2^2 - v_2 \sqrt{4v_1v_3 - v_2^2} \tan \left(\frac{1}{2} \sqrt{4v_1v_3 - v_2^2} (x - r_1t) \right)} \right], \quad (61)$$

$$\mathfrak{P}_{53}(x, t) = a_0 e^{i(r_3t + r_2(-x) + r_4)} \times \left[1 - \frac{4v_1v_3}{v_2^2 - v_2 \sqrt{4v_1v_3 - v_2^2} \cot \left(\frac{1}{2} \sqrt{4v_1v_3 - v_2^2} (x - r_1t) \right)} \right]. \quad (62)$$

$$\text{For } [v_2^2 - 4v_1v_3 < 0 \text{ \& } v_3 \neq 0]$$

$$\mathfrak{P}_{54}(x, t) = a_0 e^{i(r_3t + r_2(-x) + r_4)} \times \left[1 - \frac{4v_1v_3}{\sqrt{v_2^2 - 4v_1v_3} \tanh \left(\frac{1}{2} \sqrt{v_2^2 - 4v_1v_3} (x - r_1t) \right) + v_2^2} \right], \quad (63)$$

$$\mathfrak{P}_{55}(x, t) = a_0 e^{i(r_3t + r_2(-x) + r_4)}$$

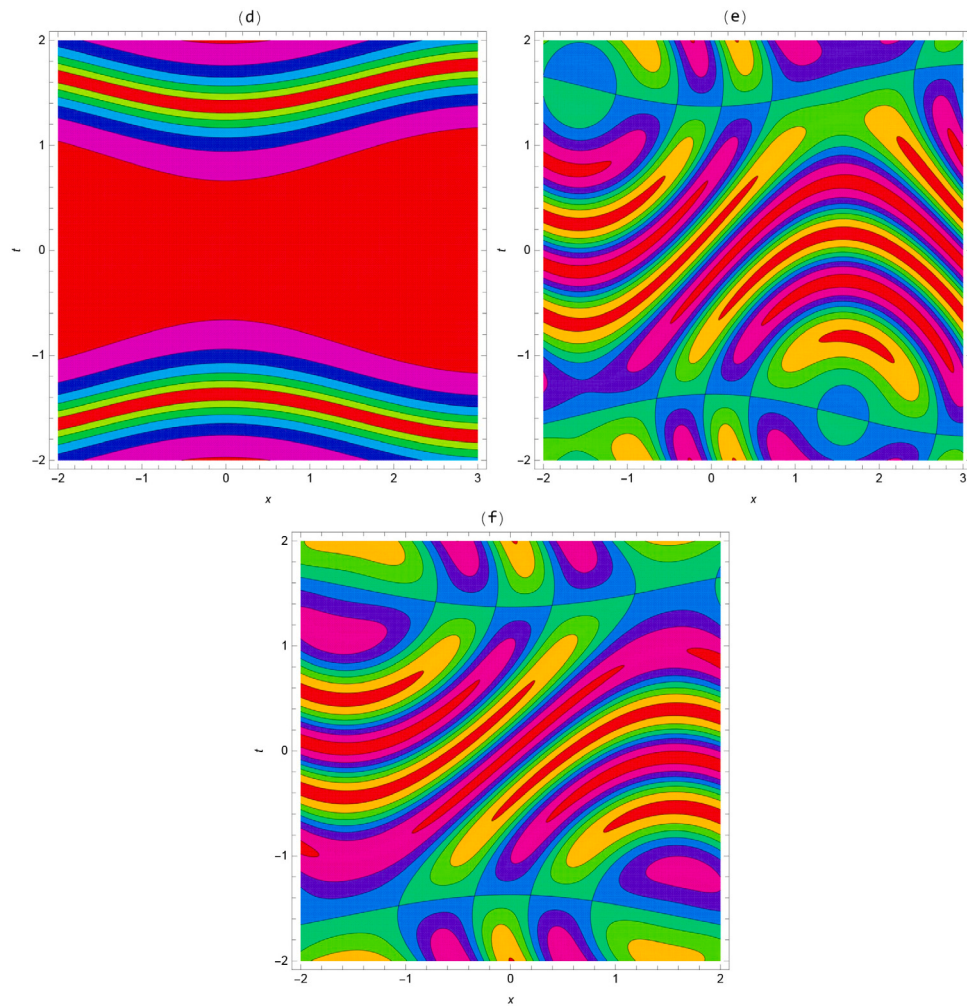


Fig. 14. Numerical simulation of absolute, real, and imaginary Eq. (57) in contour plots.

$$\times \left(1 - \frac{4v_1 v_3}{\sqrt{v_2^2 - 4v_1 v_3 v_2} \coth \left(\frac{1}{2} \sqrt{v_2^2 - 4v_1 v_3} (x - r_1 t) \right) + v_2^2} \right). \quad (64)$$

$$\text{For } \left[v_2 = \frac{v_1}{2} = \kappa \text{ \& } v_3 = 0 \right]$$

$$\mathfrak{P}_{56}(x, t) = a_0 e^{t(r_3 t + r_2(-x) + r_4)} \left(\frac{4}{e^{\kappa(x - r_1 t)} - 2} + 1 \right). \quad (65)$$

$$\text{For } \left[v_3 = 0 \text{ \& } v_2 \neq 0 \text{ \& } v_1 \neq 0 \right]$$

$$\mathfrak{P}_{57}(x, t) = a_0 e^{t(r_3 t + r_2(-x) + r_4)} \left(1 - \frac{2v_1}{v_1 - v_2 e^{v_2(x - r_1 t)}} \right). \quad (66)$$

3. Stability

In this section, we will explore the stability property of the obtained solutions using the Hamiltonian method for the dimensionless version of the Zakharov (ZE) equation. The momentum is given by the following formula:

$$\mathcal{E} = \frac{1}{2} \int_{-\mathcal{G}}^{\mathcal{G}} Y^2(\mathfrak{F}) d\mathfrak{F}, \quad (67)$$

where $\mathcal{G}$, $-\mathcal{G}$ are arbitrary constants. Thus, the condition for stability is given in the next condition:

$$\left. \frac{\partial \mathcal{E}}{\partial r_1} \right|_{r_1 = \mathfrak{R}} > 0. \quad (68)$$

where r_1 , $\mathfrak{R}$ are arbitrary constants.

Investigating the stability of the solution of Eq. (4) by using (7) with the following values of the constants $\left[a_0 = 5, b_0 = 6, \eta = 4, s_1 = 3, s_2 = 2 \right]$, yields:

$$\mathcal{E} = \frac{1}{162r_1} \left[25(25r_1 - \log(e^{-5r_1} + 2e^9) + \log(e^{5r_1} + 2e^9) - \log(e^{5r_1+1} + 2) + \log(e^{1-5r_1} + 2)) \right] \quad (69)$$

Thus,

$$\left. \frac{\partial \mathcal{E}}{\partial r_1} \right|_{r_1=2} = 0.2009804350 > 0. \quad (70)$$

This means, that this solution is stable.

Investigating the stability of the solution of Eq. (4) by using (44) with the following values of the constants $\left[b_1 = 3, a_1 = 4, A = 5, b_0 = \right]$

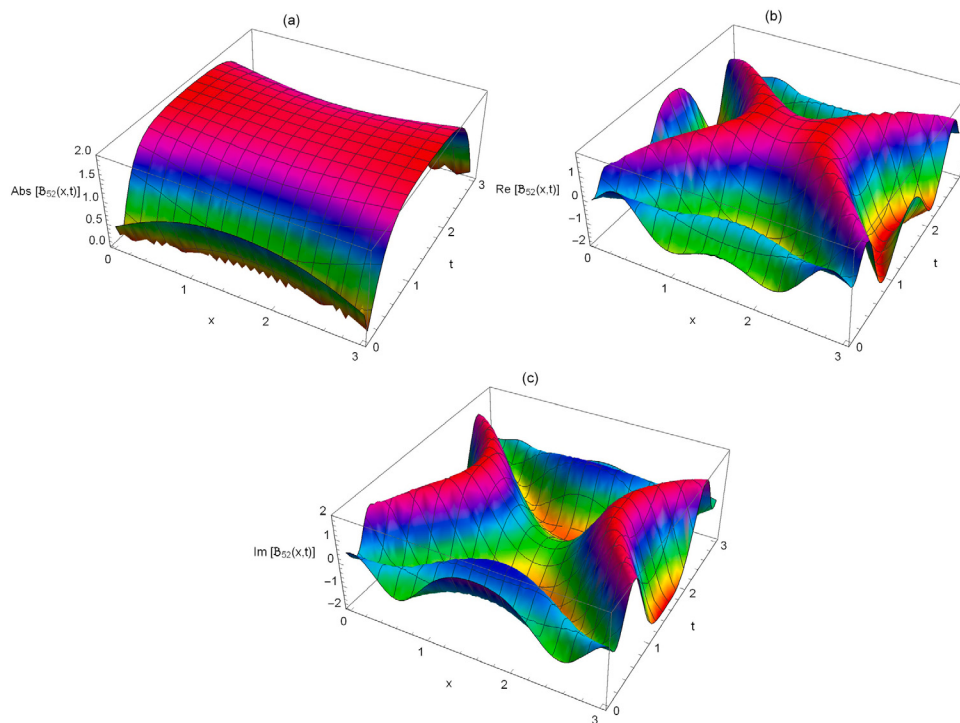


Fig. 15. Numerical simulation of absolute, real, and imaginary Eq. (61) in three-dimensional plots.

2], yields:

$$\mathcal{E} = \frac{1}{r_1} \left[32 \left(-\log(e^{-5r_1} + 5e^5) + \log(e^{5r_1} + 5e^5) \right) - \log(e^{5r_1+5} + 5) + \log(e^{5-5r_1} + 5) \right] + 800 \quad (71)$$

Thus, we obtain

$$\left. \frac{\partial \mathcal{E}}{\partial r_1} \right|_{r_1=5} = 12.79999964 > 0. \quad (72)$$

This means, this solution is stable.

Investigating the stability of the solution of Eq. (4) by using (57) with the following values of the constants $[a_0 = 1, v_2 = 5, v_1 = 3, v_3 = 2]$, yields:

$$\mathcal{E} = \frac{1}{25r_1} \left[4 \left(\log \left(\cosh \left(\frac{5}{2} (r_1 - 1) \right) \right) - \log \left(\cosh \left(\frac{5}{2} (r_1 + 1) \right) \right) \right) \right] + 2 \quad (73)$$

Thus, we obtain

$$\left. \frac{\partial \mathcal{E}}{\partial r_1} \right|_{r_1=7} = 0.01632653061 > 0. \quad (74)$$

This means, that this solution is stable, and by applying the same steps to other obtained solutions, the stability property of each one of them can be determined.

Remark. We have changed the value of the above-mentioned parameters as following $[a_0 = 9, b_0 = 3, \eta = 7, s_1 = 5, s_2 = 6 \text{ \& } a_1 = 12, A = 2, b_0 = 7, b_1 = 1 \text{ \& } a_0 = -5, v_2 = 6, v_1 = 3, v_3 = 1]$ the solution is stable, however this does not reflect the stability over all parameter ranges. It is worth to mention that the stability is preserved for wide range of parameter sets.

4. Illustration of the solutions

In this section we plot the obtained solutions are traveling wave solutions.

1. Figs. 1, 2 show the wave solution in three and contour plot respectively for the absolute, real, and imaginary values of (7) for $[a_0 = 4, b_0 = \frac{4}{5}, \eta = 1, r_1 = -2, r_2 = -3, r_3 = 2, r_4 = -1, s_1 = 5, s_2 = 6]$.
2. Figs. 3, 4 show the cone wave solution in three and contour plot respectively for the absolute, real, and imaginary values of (19) for $[a_0 = 4, b_0 = \frac{4}{5}, \eta = 1, r_1 = -2, r_2 = -3, r_3 = 2, r_4 = -1, s_1 = 5, s_2 = 6]$.
3. Figs. 5, 6 show the solitary wave solution in three and contour plot respectively for the absolute, real, and imaginary values of (31) for $[a_0 = 8, b_0 = 7, \eta = -6, r_1 = -5, r_2 = -7, r_3 = 6, r_4 = -4, s_1 = 3, s_2 = 2]$.
4. Figs. 7, 8 show the periodic solitary wave solution in three and contour plot respectively for the absolute, real, and imaginary values of (36) for $[a_0 = -2, b_0 = -3, \eta = -5, r_1 = 2, r_2 = 3, r_3 = 5, r_4 = 7, s_1 = 5, s_2 = 6]$.
5. Figs. 9, 10 show the dark solitary wave solution in three and contour plot respectively for the absolute, real, and imaginary values of (44) for $[a_1 = -2, A = 1, b_0 = 3, b_1 = 4, r_1 = 2, r_2 = 3, r_3 = 5, r_4 = 7]$.

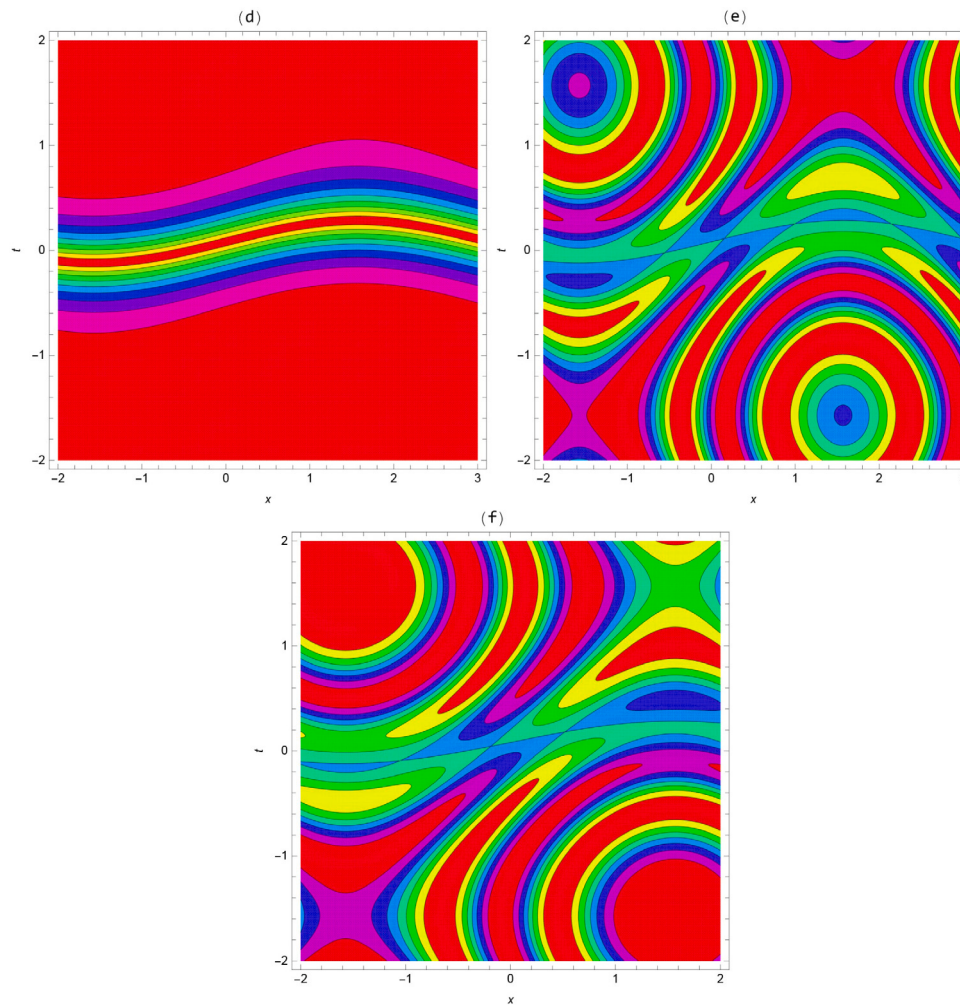


Fig. 16. Numerical simulation of absolute, real, and imaginary Eq. (61) in contour plots.

6. Figs. 11, 12 show the solitary wave solution in three and contour plot respectively for the absolute, real, and imaginary values of (48) for $\left[A = 1, q_2 = -4, r_1 = 2, r_2 = 3, r_3 = 5, r_4 = 7.\right]$
7. Figs. 13, 14 show the dark solitary wave solution in three and contour plot respectively for the absolute, real, and imaginary values of (57) for $\left[a_0 = 10, r_1 = 5, r_2 = 6, r_3 = 7, r_4 = 8, v_2 = 3, v_1 = 2, v_3 = 1.\right]$
8. Figs. 15, 16 show the bright solitary wave solution in three and contour plot respectively for the absolute, real, and imaginary values of (61) for $\left[a_0 = 10, r_1 = 5, r_2 = 6, r_3 = 7, r_4 = 8, v_2 = 5, v_1 = 2, v_3 = 3.\right]$

5. The paper novelty

The novelty of our paper, which explains the originality of our results, is discussed in this section. Three recent computational schemes (the extended $\exp(\phi)$ -expansion method, generalized Kudryashov method, and the modified Khater method) are employed to construct distinct types of solutions for the dimensionless form of the Zakharov (ZE) equation. These solutions explain more novel properties for the interaction between (low & high) frequency of (ion-acoustic & Langmuir) waves in plasma. Applying all these schemes to the dimensionless form of the Zakharov equation we deduce that:

1. Applied methods:

- The modified Khater method reproduces the same results as the extended $\exp(\phi)$ -expansion method For $\left[s_2 = v_3, s_3 = v_1, s_1 = v_2, \Gamma = e, e^{\phi(\xi)} = \Gamma^{\mathfrak{S}(\xi)}\right]$.
- The modified Khater method reproduces the same results as the generalized Kudryashov method when $\left[\Gamma^{\mathfrak{S}(\xi)} = \mathfrak{Q}(\xi), v_1 = 0, v_3 = 1, v_2 = -1\right]$.

2. Obtained solutions

- According to the equivalence between these methods some of the obtained solutions are leading to recover the solutions obtained in all previous research papers with this model.
- Comparison between our obtained solutions and that have been collected in [42,43,46–48], shows that our paper where our obtained solutions are recovering these obtained solutions in these papers. Moreover, we note that we have determined novel solutions of this model have been never found previously.

6. Conclusion

In the dimensionless shape of the Zakharov (ZE) equation, multi-soliton waves, periodic waves, dark waves, light waves, and wave solutions have been derived. To analyze new dynamic and physical actions of the interaction between (low & high) frequency and (ion-acoustic & Langmuir) waves in plasma, three recent analytical schemes have been used. The stability property of the obtained solutions has been tested. Several figures have been plotted to illustrate the dynamics of the solutions in the three-dimensional and contour map. We have recovered the previous solutions of this model and we have derived new exact solutions in closed-form that never been generated previously.

CRediT authorship contribution statement

Mostafa M.A. Khater: Conceptualization, Data curation, Formal analysis, Funding acquisition, Investigation, Methodology, Project administration, Resources, Software, Supervision, Visualization, Writing - original draft, Writing - review & editing. **Raghda A.M. Attia:** Conceptualization, Data curation, Formal analysis, Funding acquisition, Methodology, Project administration, Visualization, Writing - original draft, Writing - review & editing. **Emad E. Mahmoud:** Data curation, Investigation, Resources, Software, Supervision, Writing - review & editing. **Abdel-Haleem Abdel-Aty:** Conceptualization, Data curation, Funding acquisition, Methodology, Project administration, Software, Validation, Visualization, Writing - review & editing. **Kholod M. Abualnaja:** Formal analysis, Funding acquisition, Investigation, Resources, Supervision, Visualization, Writing - review & editing. **A.-B.A. Mohamed:** Formal analysis, Investigation, Validation, Writing - review & editing. **Hichem Eleuch:** Formal analysis, Methodology, Software, Validation, Writing - review & editing.

Declaration of competing interest

The authors declare that they have no known competing financial interests or personal relationships that could have appeared to influence the work reported in this paper.

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